



# ***Using Python to run NEURON***

# ***Everything is the same (but different)***

- ⑥ All underlying simulation objects must be same
- ⑥ All underlying simulation calls must be same
- ⑥ Various useful and important ancillary things are available
- ⑥ Most of these (eg vectors, lists) map 1-to-1 on native Python objects

# *Compiling –with-nrnpython*



- ⑥ many configuration options
- ⑥ –with-nrnpython Python interpreter can be used (default is NO) Probably need to set PYLIBDIR to find libpython and PYINC DIR to find Python.h
- ⑥ –with-paranrn

# *What environment?*

- ⑥ nrniv -python
- ⑥ python: from neuron import h
- ⑥ python: from neuron import gui
- ⑥ python vs ipython
- ⑥ sage

# *Python advantages*

- ⑥ Widely used
- ⑥ Readily extensible
- ⑥ Many plugins/toolboxes
- ⑥ Easy yet hard
- ⑥ Easy arg calls
- ⑥ Elegant (maybe too much so)

# *Advantages for NEURON*

- ⑥ All legacy models work
- ⑥ Better representation of concepts
- ⑥ Uniform approach to objects
- ⑥ Connect to other tools: numpy, scipy, . . .

# Preliminaries

- ⑥ Helpful: `dir(soma)`, `help(soma)`
- ⑥ `h` is function or object
- ⑥ `h()` executes arbitrary hoc
- ⑥ `h.thing` then accesses thing

# An example

```
>>> h(''x = 5
... strdef s
... s = "hello"
... func square() { return \"$1*\"$1 } ''')
```

- ⑥ now access with `h`.
- ⑥ `print h.x,h.s` # print is a python command
- ⑥ `h("print x,s // print is a hoc command")`
- ⑥ `x=h.square(10)` # x is a python variable
- ⑥ Looks silly (and confusing) but needed for legacy



# *Making new things*

- ⑥ 'create soma' → `soma=h.Section()`
- ⑥ 'stim=new IClamp()' → `stim=h.IClamp()`
- ⑥ *soma insert hh* → `soma.insert('hh')`

## ⑥ *Note potential for massive screw-ups*



- ⑥ 2 languages → can make **2 different things with same name**
- ⑥ `soma=h.Section(); soma.L=20; h('create soma')`
- ⑥ `print soma.L,h.soma.L # different`
- ⑥ To avoid this: **`h('create soma'); soma=h.soma`**
- ⑥ Important for shape plots etc.

# Accessing segments

- ⑥ `soma for (x) gnabar_hh(x)=3e-3*x →`
- ⑥ `for seg in soma: seg.gnabar_hh=3e-3*seg.x;`
- ⑥ Can also still access segments relatively:
- ⑥ `soma print gnabar_hh(0.5) →`
- ⑥ `soma(0.5).hh.gnabar`

## *More placement: insert vs PPs*

- ⑥ `soma stim = new IClamp(0.5)`
- ⑥ `stim = h.IClamp(soma(0.5))`
- ⑥ *Setting is the same:*
- ⑥ `stim.amp=0.1; stim.dur=10; stim.delay=100`

# *Template (hoc) → class (py)*

**in hoc:**

```
begintemplate Cell
  proc init() {
    topology()
    subsets()
    ...
  }
  ...
endtemplate Cell
```

# *Template (hoc) → class (py)*

**in python:**

```
class Cell(object):  
    def __init__(self):  
        self.topology()  
        self.subsets()  
        ...
```

# Setting up topology

```
def topology(self):  
    self.soma = h.Section(cell = self)  
    self.dend = h.Section(cell = self)  
    self.dend.connect(self.soma)
```

# *Some things are hard to find*

- ⑥ how to find optional arguments?
- ⑥ `inspect.isbuiltin(h.Section) # true`
- ⑥ `inspect.getmembers(h.Section())`
- ⑥ `src/nrnpython/nrnpy_nrn.cpp`